

## Lecture 22

Think I can say what makes H-J method powerful:

H-J eqn is 1<sup>st</sup> order

$$H\left(\frac{\partial S}{\partial p}, q\right) + \frac{\partial S}{\partial t} = 0$$

So if equation separates

$$S = S_1(q_1) + S_2(q_2) + \dots + S_0(t)$$

then each  $S_i$  satisfies first order ODE

Can solve any 1<sup>st</sup> order ODE by integration

Not true for 2<sup>nd</sup> & higher order ODEs,  
such as from Lagrangian

So using H-J method, any separable system can be solved

Coord is separable if  $q_i$  &  $p_i$  appear only as  $f(p_i, q_i)$  in  $H(p, q)$

Example: Spherical coords  $(r, \theta, \phi)$

$$H = \frac{1}{2m} \left( p_r^2 + \frac{p_\theta^2}{r^2} + \frac{p_\phi^2}{r^2 \sin^2 \theta} \right) + V(r, \theta, \phi)$$

Say  $V = \frac{a(\phi)}{r^2 \sin^2 \theta} + b(r, \theta)$

$$\text{then } H = \frac{1}{2m} \left( p_r^2 + \frac{p_\theta^2}{r^2} + b(r, \theta) \right) + \frac{1}{r^2 \sin^2 \theta} \underbrace{\left( p_\phi^2 + a(\phi) \right)}_{f(\phi, p_\phi)}$$

$\phi$  separates

Go through:

$$S(r, \theta, \phi, t) = W(r, \theta) + \Phi(\phi) - Et$$

$$S_0 \quad \frac{1}{2m} \left[ \left( \frac{\partial W}{\partial r} \right)^2 + \frac{1}{r^2} \left( \frac{\partial W}{\partial \theta} \right)^2 + \frac{1}{r^2 \sin^2 \theta} (\Phi')^2 \right] + \frac{a(\phi)}{r^2 \sin^2 \theta} + b(r, \theta) - E = 0$$

$$\frac{r^2 \sin^2 \theta}{2m} \left[ \left( \frac{\partial W}{\partial r} \right)^2 + \frac{1}{r^2} \left( \frac{\partial W}{\partial \theta} \right)^2 + 2mb - 2mE \right] = - \left[ (\Phi')^2 + a(\phi) \right]$$

$$= -\alpha_\phi \text{ const}$$

$$S_0 \quad \left( \frac{d\Phi}{d\phi} \right)^2 + a = \alpha_\phi$$

$$\underline{\Phi} = \pm \int \sqrt{\alpha_\phi - a(\phi)} d\phi$$

Left with 2D eqn:

$$\frac{1}{2m} \left[ \left( \frac{\partial W}{\partial r} \right)^2 + \frac{1}{r^2} \left( \frac{\partial W}{\partial \theta} \right)^2 \right] + b - E + \frac{2m\alpha_\phi}{r^2 \sin^2 \theta} = 0$$

Reduced to 2D problem with  $V_{\text{eff}}(r, \theta) = b(r, \theta) + \frac{2m\alpha_\phi}{r^2 \sin^2 \theta}$

Compare to Lagrangian:

$$L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2 + r^2 \sin^2 \theta \dot{\phi}^2) - \frac{a(\phi)}{r^2 \sin^2 \theta} - b(r, \theta)$$

$$\text{Egns:} \quad m \ddot{r} - \left( m r \dot{\theta}^2 + m r \sin^2 \theta \dot{\phi}^2 - \frac{\partial b}{\partial r} \right) = 0$$

$$\frac{d}{dt} (m r^2 \dot{\theta}) - \left( m r^2 \sin \theta \cos \theta \dot{\phi}^2 - \frac{\partial b}{\partial \theta} \right) = 0$$

$$\frac{d}{dt} (m r^2 \sin^2 \theta \dot{\phi}) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial a}{\partial \phi} = 0$$

No obvious way to eliminate  $\phi$

Landau & Lifshitz list separability criteria for spherical, parabolic, elliptic coords

So if system is separable, solution reduced to integrals.

Usually, integrals can't be done

Can often go further if a system is also periodic

Two flavours: a)  $p \times q$  periodic fcn of time

System returns to initial state,  
like harmonic oscillator

Cell cycle = "libration"

b)  $p$  is periodic fcn of  $q$

Like pendulum swinging over top  
 $\theta$  keeps increasing, but still  
periodic

Cell cycle = "rotation"

Can often get period even if not full solution

use "action-angle" variables

Action variable  $J_r \equiv \oint p_r dq_r$  over one period

Since separable, know  $p_r = \frac{\partial S}{\partial q_r} = \frac{dW_r}{dq_r}$

Remember, separation const's  $\alpha_r$  also in  $W$

$$\Rightarrow \text{So } p_r = p_r(q_r, \alpha\text{'s})$$

$$\Rightarrow J_r = J_r(\alpha\text{'s})$$

$\alpha$  = combination of constants

Assume relation invertible:

$$\alpha_r = \alpha_r(J\text{'s})$$

Express action  $S(q\text{'s}, \alpha\text{'s}, t)$  in terms of  $J\text{'s}$ :

$$= \bar{S}(q\text{'s}, J\text{'s}, t)$$

In particular, say  $\alpha_1 = \text{sep constant for } t$

$$\text{So } \bar{S} = \bar{W}(q\text{'s}, J\text{'s}) - \alpha_1(J_1) t$$

$\bar{S}$  is still action, just with constants rearranged

$$\text{So } p_r = \left( \frac{\partial \bar{S}}{\partial q_r} \right)_{J\text{'s}} \quad \bar{Q}_r = \left( \frac{\partial \bar{S}}{\partial J_r} \right)_{q\text{'s}} = \text{constant} \\ = \bar{\beta}_r$$

$$\bar{\beta}_r = \left( \frac{\partial \bar{W}}{\partial J_r} \right)_{q\text{'s}} - \frac{\partial \alpha_1}{\partial J_r} t$$

Define "angle variable"  $W_r = \left( \frac{\partial \bar{W}}{\partial J_r} \right)_{q\text{'s}}$   
= fun of  $q\text{'s}$

$$\text{Then } \omega_{\sigma} = \beta_{\sigma} + \frac{\partial \alpha_{\sigma}}{\partial J_{\sigma}} t$$

↑ constants ↑

$\omega_{\sigma}$  increases linearly in time  
(like angle in const rotation)

$$\text{Rate } \frac{\partial \alpha_{\sigma}}{\partial J_{\sigma}} = \frac{\partial E}{\partial J_{\sigma}} \equiv \nu_{\sigma}$$

In fact,  $\nu_{\sigma} = \text{oscillation freq for mode } \sigma$

Slow example first, then prove:

$$H = \frac{p^2}{2m} + \frac{1}{2} k q^2 = E$$

$$\text{So } p = \pm \sqrt{2mE - mkq^2}$$

$$J = \oint p dq = \oint \sqrt{2mE - mkq^2} dq$$

$$\text{To integrate set } q = \sqrt{\frac{2E}{k}} \sin \theta$$

$$dq = \sqrt{\frac{2E}{k}} \cos \theta$$

$$J = \int_0^{2\pi} \sqrt{2mE(1 - \sin^2 \theta)} \sqrt{\frac{2E}{k}} \cos \theta d\theta$$

$$= 2E \sqrt{\frac{m}{k}} \int_0^{2\pi} \cos^2 \theta d\theta$$

$$= 2E \sqrt{\frac{m}{k}} \pi$$

$$\text{Or } E = \frac{1}{2\pi} J \sqrt{\frac{k}{m}}$$

$$\nu = \frac{\partial E}{\partial J} = \frac{1}{2\pi} \sqrt{\frac{k}{m}} \quad \text{correct!}$$

Prove in general:

Assume entire system periodic  
not just individual coords

→ requires individual freqs to be commensurate

$$\Delta t = N_1 \tau_1 = N_2 \tau_2 = \dots = N_n \tau_n \quad \text{integers } N_\sigma$$

If not true, then system arbitrarily close to  
one that is (N's can be large)

In time  $\Delta t$ , angle variable  $w_\lambda$  changes by

$$\Delta w_\lambda = \nu_\lambda \Delta t = N_\lambda \nu_\lambda \tau_\lambda \quad *$$

But also know

$$\begin{aligned} dw_\lambda &= \sum_\sigma \frac{\partial w_\lambda}{\partial q_\sigma} dq_\sigma \\ &= \sum_\sigma \frac{\partial}{\partial q_\sigma} \left( \frac{\partial \bar{w}}{\partial J_\lambda} \right) dq_\sigma \\ &= \frac{\partial}{\partial J_\lambda} \sum_\sigma \frac{\partial \bar{w}}{\partial q_\sigma} dq_\sigma \end{aligned}$$

$$dw_\lambda = \frac{\partial}{\partial J_\lambda} \sum_\sigma p_\sigma dq_\sigma$$

Integrate over time  $\Delta t$ :

$$\begin{aligned} \Delta w_\lambda &= \frac{\partial}{\partial J_\lambda} \sum_\sigma \underbrace{\int_{\Delta t} p_\sigma dq_\sigma}_{\text{}} \\ &= N_\sigma \oint p_\sigma dq_\sigma \\ &= N_\sigma J_\sigma \end{aligned}$$

$$\text{So } \Delta \omega_\lambda = \frac{\partial}{\partial J_\lambda} \sum_{\sigma} N_{\sigma} J_{\sigma} = N_{\lambda}$$

$$\text{Combine with * : } N_{\lambda} \nu_{\lambda} T_{\lambda} = N_{\lambda}$$

$$\nu_{\lambda} = \frac{1}{T_{\lambda}} = \text{freq for } \lambda:$$

Useful any time you can express p's as fns of q's

Harder example: Kepler problem

$$H = \frac{p_r^2}{2m} + \frac{p_{\phi}^2}{2mr^2} - \frac{\gamma m}{r}$$

$$\text{H-J: } \frac{1}{2m} \left( \frac{\partial S}{\partial r} \right)^2 + \frac{1}{2mr^2} \left( \frac{\partial S}{\partial \phi} \right)^2 - \frac{\gamma m}{r} + \frac{\partial S}{\partial t} = 0$$

Since  $\phi$  not cyclic, separation is trivial

$$S = W(r) - Et + l\phi$$

$$\frac{1}{2m} \left( \frac{dW}{dr} \right)^2 + \frac{l^2}{2mr^2} - \frac{\gamma m}{r} - E = 0$$

$$\text{Note: } p_{\phi} = \frac{\partial S}{\partial \phi} = l$$

$$p_r = \frac{\partial S}{\partial r} = \frac{dW}{dr} = \pm \left( 2mE + \frac{2\gamma m^2}{r} - \frac{l^2}{r^2} \right)^{1/2}$$

Get action variables

$$J_{\phi} = \oint p_{\phi} d\phi = l \oint d\phi = 2\pi l$$

$$J_r = \pm \oint \sqrt{\quad} dr$$

How does  $r$  vary over cycle?

Bounded by classical turning points

$$2mE + \frac{2\gamma m^2}{r} - \frac{l^2}{r^2} = 0$$

Quadratic in  $r$ : roots  $r_1 = -\frac{1}{E} \left( \gamma m - \sqrt{\gamma^2 m^2 + \frac{2El^2}{m}} \right)$

$$r_2 = -\frac{1}{E} \left( \gamma m + \sqrt{\gamma^2 m^2 + \frac{2El^2}{m}} \right)$$

Remember  $E < 0$  ... see  $0 < r_1 < r_2$

$$J_r = \oint p_r dr = 2 \int_{r_1}^{r_2} \sqrt{2mE + \frac{2\gamma m^2}{r} - \frac{l^2}{r^2}} dr$$

Know that  $r_1, r_2$  factor root: get

$$J_r = 2\sqrt{-2mE} \int_{r_1}^{r_2} \frac{1}{r} \sqrt{(r_2 - r)(r - r_1)} dr$$

$$= 2\sqrt{-2mE} \int_{r_1}^{r_2} \frac{1}{r} \sqrt{-r^2 + (r_1 + r_2)r - r_1 r_2} dr$$

Look up formula

$$\int \frac{1}{u} \sqrt{Au^2 + Bu + C} du = \sqrt{Au^2 + Bu + C} - 2\sqrt{-A} \sin^{-1} \left( \frac{2Au + B}{\sqrt{B^2 - 4AC}} \right) - \sqrt{-C} \sin^{-1} \left( \frac{Bu + 2C}{u\sqrt{B^2 - 4AC}} \right)$$

for  $A, C < 0$

Put in  $A = -1$ ,  $B = r_1 + r_2$ ,  $C = -r_1 r_2$

$u = r_2$  and  $r_1$

Not so bad...

$$B^2 - 4AC = (r_1 + r_2)^2 - 4r_1 r_2 = (r_1 - r_2)^2$$

$$\sqrt{\quad} = |r_1 - r_2| = r_2 - r_1$$

Eval at  $r_2$ :  $\sqrt{Au^2 + Bu + C} = 0$

$$\text{Get } -\frac{r_1 + r_2}{2} \sin^{-1} \frac{-2r_2 + r_1 r_2}{r_2 - r_1}$$

$$- \sqrt{r_1 r_2} \sin^{-1} \left( \frac{(r_1 + r_2)(r_2) - 2r_1 r_2}{r_2(r_2 - r_1)} \right)$$

$$= -\frac{r_1 + r_2}{2} \sin^{-1} \left( \frac{r_1 - r_2}{r_2 - r_1} \right) - \sqrt{r_1 r_2} \sin^{-1} \left( \frac{r_2(r_2 - r_1)}{r_2(r_2 - r_1)} \right)$$

$$= -\frac{r_1 + r_2}{2} \left( -\frac{\pi}{2} \right) - \sqrt{r_1 r_2} \left( \frac{\pi}{2} \right)$$

$$= \frac{\pi}{4} (r_1 + r_2 - 2\sqrt{r_1 r_2})$$

Eval at  $r_1$  get  $-\frac{\pi}{4} (r_1 + r_2 - 2\sqrt{r_1 r_2})$

$$\text{So } \int_{r_1}^{r_2} = \frac{\pi}{2} (r_1 + r_2 - 2\sqrt{r_1 r_2})$$

and  $J_r = \pi \sqrt{-2mE} (r_1 + r_2 - 2\sqrt{r_1 r_2})$

From  $r_1 + r_2$  have

$$r_1 + r_2 = -\frac{2\gamma m}{E}$$

$$r_1 r_2 = -\frac{2l^2}{mE}$$

$$J_r = 2\pi \sqrt{-2mE} \left( -\frac{\gamma m}{E} - 2\sqrt{\frac{-l^2}{2mE}} \right)$$

$$2\pi \left( \sqrt{\frac{2m^3 \gamma^2}{-E}} - 2|l| \right)$$

To use action-angle result, solve for  $E(J_r, J_\phi)$

$$J_\phi = 2\pi l$$

$$\text{so } J_r = 2\pi \sqrt{\frac{2m^3 g^2}{-E}} - 2J_\phi$$

$$J_r + 2J_\phi = 2\pi \left( \frac{2m^3 g^2}{-E} \right)^{1/2}$$

$$E = - \frac{8\pi^2 m^3 g^2}{(J_r + 2J_\phi)^2}$$

Then frequencies are

$$\omega_\phi = \frac{\partial E}{\partial J_\phi} = \frac{32\pi^2 m^3 g^2}{(J_r + 2J_\phi)^3}$$

$$\text{Use } J_r + 2J_\phi = 2\pi \left( \frac{2m^3 g^2}{-E} \right)^{1/2}$$

$$\text{so } \omega_\phi = \frac{32\pi^2 m^3 g^2}{8\pi^3 (2m^3 g^2)^{3/2} (-E)^{3/2}}$$

$$= \frac{4}{\pi} \frac{1}{2^{3/2}} \frac{1}{\sqrt{m^3 g^2}} (-E)^{-3/2}$$

$$\omega_\phi = \frac{\sqrt{2}}{\pi} \frac{L}{g m^{3/2}} (-E)^{-3/2}$$

agrees w/ ch 1 result... works!

Similar problem in HW...  $\vec{L}$  in arb direction,  
not along  $\hat{z}$